

Contents

List of Figures	IX
Foreword	XIII
Part I	
Theory of elasticity	1
Chapter 1 – Outline of linear algebra	3
1.1 Vector spaces and linear mappings	3
1.1.1 Vector spaces	3
1.1.2 Linear mappings	4
1.2 Euclidean spaces	8
1.2.1 Euclidean metric tensor and scalar product	9
1.2.2 Eigenvalues and eigenvectors	10
1.3 Tensors	11
1.3.1 Tensors and linear mappings	11
1.4 Coordinate systems	13
1.4.1 Linear mappings and the metric tensor	14
1.4.2 Components of the metric tensor	15
1.4.3 Examples of coordinate systems	17
1.4.4 Volumes and the vector product	21
1.5 Covariant differentiation	24
1.5.1 Grad, div, curl and Laplace's operator	25
1.6 Affine space	29
1.6.1 Free and applied vectors	29
1.7 Surfaces	32
Chapter 2 – Analysis of strain	37
2.1 Introduction	37
2.2 Deformation	38
2.3 Strain tensor in general coordinates	38
2.3.1 Examples of strain in Cartesian coordinates	44
2.3.2 Infinitesimal deformations	48
2.3.3 Deformation and rigid body motion	49
2.4 Shell continuum	51

2.4.1	General assumptions	51
2.4.2	Strain tensor	52
Chapter 3 – Analysis of stress		57
3.1	Body and surface forces	57
3.2	State of stress	58
3.2.1	Stress vector components	61
3.2.2	Stress tensor	61
3.3	Equations of equilibrium	64
3.3.1	Translational equilibrium	64
3.3.2	Rotational equilibrium	65
3.4	Principal stresses and principal directions	67
3.4.1	Normal and tangential components of the stress vector	69
3.4.2	Mohr's circles	70
3.5	Stress quadric of Cauchy	77
3.6	Stress-deviator and spherical components of the stress tensor	78
3.7	Stress in shell continuums	79
3.7.1	Shifters	79
3.7.2	Contraction of surface forces	80
3.7.3	Body forces and load density	84
3.7.4	Eulero's equations	85
3.7.5	Membrane state of stress	88
Chapter 4 – Equations of elasticity		89
4.1	The material law	89
4.1.1	Generalized Hooke's law	90
4.2	The linear elastic problem	95
4.2.1	Boundary value problem in terms of stresses	96
4.2.2	Boundary value problem in terms of displacements	98
4.3	Constitutive equation for shell continuums	100
Chapter 5 – Principle of Virtual Work		103
5.1	Virtual work	103
5.1.1	A simple example	107
5.2	PVW, Compatibility conditions, Equilibrium	109
Chapter 6 – Energy principles and variational methods		111
6.1	The strain-energy function and Hooke's law	111
6.1.1	Superposition principle	116
6.1.2	Uniqueness of the solution	117
6.1.3	Theorem of reciprocity	119

6.2 Variational methods	120
6.2.1 Potential energy	120
6.2.2 Complementary energy	122
6.2.3 Theorems of Castigliano	124
Chapter 7 – Strength of materials	129
7.1 Introduction	129
7.2 Maximum stress theory	130
7.3 Maximum strain theory	131
7.4 Beltrami’s theory	132
7.5 Von Mises’ criterion	132
7.6 Criteria comparison	134
7.6.1 Maximum stress	134
7.6.2 Maximum strain	135
7.6.3 Beltrami’s criterion	136
7.6.4 Von Mises’ criterion	137
7.6.5 Comparison	138
Part II. Theory of elastic beams	141
Chapter 8 – Saint-Venant’s problem	143
8.1 Statement of the problem	143
8.1.1 External and internal forces	148
8.2 Four fundamental cases	153
8.3 Beam under axial force	154
8.3.1 State of stress	154
8.3.2 State of strain	155
8.3.3 Displacement field	155
8.3.4 Strain energy	157
8.4 Beam under terminal couples	158
8.4.1 Introductory sketch	158
8.4.2 State of stress	159
8.4.3 State of strain	162
8.4.4 Displacement field	164
8.4.5 Strain energy	167
8.5 Beam under torsional couples	169
8.5.1 Circular bar	169
8.5.2 Cylindrical bar	172
8.5.3 State of strain	176
8.5.4 Displacement field	176
8.5.5 Strain energy	178
8.5.6 Torsion of tubular beams: Bredt’s theory	181
8.6 Bending and shear	184

8.6.1	External forces	184
8.6.2	State of normal stress	185
8.6.3	State of tangential stress: Jourawski's theory	187
8.6.4	Tangential stress for symmetrical cross-sections	189
8.6.5	State of strain	193
8.6.6	Total strain energy	197
8.6.7	Rectangular cross-section	198
Part III. Appendix		201
A – Applications of the shell theory		203
A.1	Spherical dome	203
A.1.1	Geometry	203
A.1.2	Displacements and strains	204
A.1.3	Equilibrium and constitutive law	205
A.2	Cylindrical shell	208
A.2.1	Geometry	208
A.2.2	Displacements and strains	209
A.2.3	Equilibrium and constitutive law	209
A.3	Hyperboloid of one sheet	211
A.3.1	Geometry	211
A.3.2	Equilibrium	215